

B. jacobnmf

Calculates the Jacobian matrix of an n -dimensional function of m variables using forward differences. *jacobnmf* computes first order difference quotient approximations

$J_{ij} = \frac{(f_i(x_1, \dots, x_{j-1}, x_j + \delta_p, x_{j+1}, \dots, x_m) - f_i(x_1, \dots, x_{j-1}, x_j, x_{j+1}, \dots, x_m)) / \delta_p}{(i, j = 1, \dots, n; j = 1, \dots, m)}$

to the partial derivatives $J_{ij} = \partial f_i(x) / \partial x_j$ of the components of the function $f(x)$ ($f \in R^n, x \in R^m$).

Function Parameters:

void *jacobnmf* (*n,m,x,f,jac,di,funct*)

n: int;

entry: the number of function components;

m: int;

entry: the number of independent variables;

x: float *x[1:m]*;

entry: the point at which the Jacobian has to be calculated;

f: float *f[1:n]*;

entry: the values of the function components at the point given in array *x*;

jac: float *jac[1:n, 1:m]*;

exit: the Jacobian matrix in such a way that the partial derivative of *f[i]* with respect to *x[j]* is given in *jac[i,j]*, $i=1, \dots, n$, $j=1, \dots, m$;

di: float (**di*)(*i*), int *i*;

entry: the partial derivatives to *x[i]* are approximated by forward differences, using an increment in the *i*-th variable equal to the value of *di*, $i=1, \dots, m$;

funct: void (**funct*)(*n,m,x,f*);

entry: the meaning of the parameters of the function *funct* is as follows:

n: the number of function components;

m: the number of independent variables of the function *f*;

x: the independent variables are given in *x[1:m]*;

f: after a call of *funct* the function components should be given in *f[1:n]*.

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void jacobnmf(int n, int m, float x[], float f[], float **jac,
               float (*di)(int), void (*funct)(int, int, float[], float[]))
{
    float *allocate_real_vector(int, int);
    void free_real_vector(float *, int);
    int i,j;
    float step,aid,*f1;

    f1=allocate_real_vector(1,n);
    for (i=1; i<=m; i++) {
        step=(*di)(i);
        aid=x[i];
        x[i]=aid+step;
        step=1.0/step;
        (*funct)(n,m,x,f1);
        for (j=1; j<=n; j++) jac[j][i]=(f1[j]-f[j])*step;
        x[i]=aid;
    }
    free_real_vector(f1,1);
}
```